

Processes as Formulas, and Choreographies as Proofs

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Based on joint works with Giulia Manara and Fabrizio Montesi

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What I want

An elegant logical framework
to reason about concurrent programs and
to design concurrent programming languages

Example: choreographic programming

Idea behind choreographic programming: specify the system globally...

$$C, C_\ell := \begin{array}{l} 0 \\ \text{end} \end{array} \mid \begin{array}{l} [p.x \rightarrow q.y]; C \\ \text{communication} \end{array} \mid \begin{array}{l} p.L \rightarrow q.L' : k \\ \text{choice} \end{array} \left\{ \begin{array}{l} \ell : C_\ell \mid \ell \in L \\ \ell : S_\ell \mid \ell \in L' \setminus L \end{array} \right\} \mid \begin{array}{l} (\nu x) C^x \\ \text{restriction} \end{array}$$

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...and then compile local programs

$$\text{EPP}(C) = \text{EPP}_{p_1}(C) \mid \cdots \mid \text{EPP}_{p_n}(C)$$

Main benefit: deadlock-free by design

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Question: are choreographies complete wrt deadlock-freedom?

- 1 Context
- 2 The π -Calculus
- 3 Processes as Formulas
- 4 Proofs in PiL as computation trees
- 5 Proof nets
- 6 Conclusion and Future work

Context

Off-the-shelf Solutions

Dynamic logics

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interleaving

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Kleene Algebra + $\underbrace{\text{commutations}}_{\text{interleaving}}$ $\xRightarrow{\text{Kozen '96}}$ undecidability whether $\alpha = \beta$

Thus

in any “concurrent-PDL” $\vdash [\alpha] \top \Leftrightarrow [\beta] \top$ is undecidable¹

¹A possible solution is to separate the trace reasoning from the operational semantics (A. et al '24 "On Propositional Dynamic Logic and Concurrency")

Session types

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Binary session types: strong restriction or syntactically complex

Multiparty session types: bad compositionality properties

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Why?

Struggling to model interleaving.

Computatation-as-deduction

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	Program	=	Inference system
Current state of a program		=	Sequent
	Execution	=	Proof search

Computation-as-deduction

Program = Inference system
Current state of a program = Sequent
Execution = Proof search

Non-determinism

don't care VS don't know
interleaving "conflict"

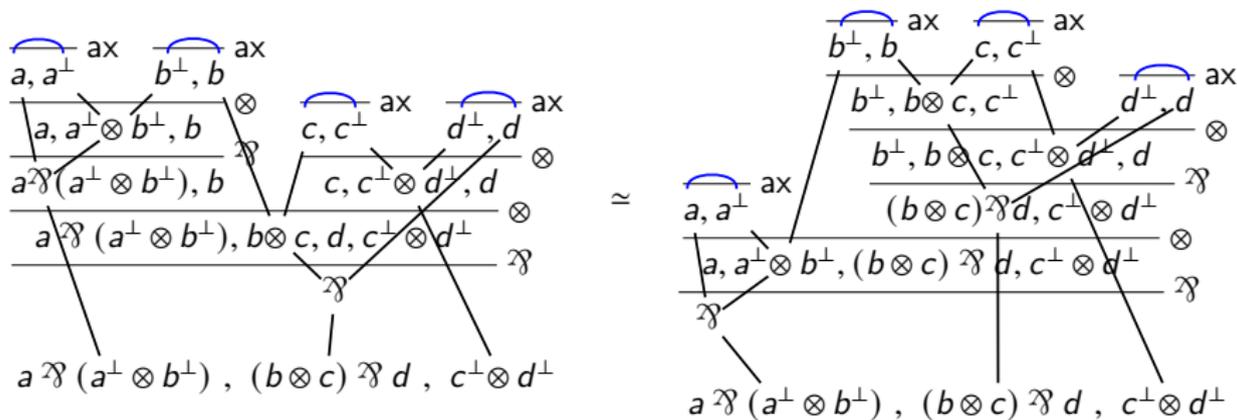
Good news everyone!

We have syntaxes capturing the “don’t care” non-determinism!

$$\begin{array}{c}
 \frac{\frac{\frac{\overline{a, a^\perp} \text{ ax}}{a, a^\perp \otimes b^\perp, b} \otimes \frac{\frac{\overline{b^\perp, b} \text{ ax}}{b^\perp, b} \otimes \frac{\overline{c, c^\perp} \text{ ax}}{c, c^\perp \otimes d^\perp, d} \otimes \frac{\overline{d^\perp, d} \text{ ax}}{d^\perp, d}}{a \wp (a^\perp \otimes b^\perp), b} \otimes \frac{\overline{c, c^\perp} \text{ ax}}{c, c^\perp \otimes d^\perp, d} \otimes \frac{\overline{d^\perp, d} \text{ ax}}{d^\perp, d}}{a \wp (a^\perp \otimes b^\perp), b \otimes c, d, c^\perp \otimes d^\perp} \otimes \\
 \frac{\overline{a \wp (a^\perp \otimes b^\perp), (b \otimes c) \wp d, c^\perp \otimes d^\perp}}{a \wp (a^\perp \otimes b^\perp), (b \otimes c) \wp d, c^\perp \otimes d^\perp}
 \end{array}
 \approx
 \begin{array}{c}
 \frac{\frac{\frac{\overline{b^\perp, b} \text{ ax}}{b^\perp, b} \otimes \frac{\overline{c, c^\perp} \text{ ax}}{c, c^\perp} \otimes \frac{\overline{d^\perp, d} \text{ ax}}{d^\perp, d}}{b^\perp, b \otimes c, c^\perp} \otimes \frac{\overline{d^\perp, d} \text{ ax}}{d^\perp, d}}{\frac{b^\perp, b \otimes c, c^\perp \otimes d^\perp, d}{(b \otimes c) \wp d, c^\perp \otimes d^\perp} \otimes \frac{\overline{a, a^\perp} \text{ ax}}{a, a^\perp}}{\frac{a, a^\perp \otimes b^\perp, (b \otimes c) \wp d, c^\perp \otimes d^\perp}{a \wp (a^\perp \otimes b^\perp), (b \otimes c) \wp d, c^\perp \otimes d^\perp} \otimes \frac{\overline{a \wp (a^\perp \otimes b^\perp), (b \otimes c) \wp d, c^\perp \otimes d^\perp}}{a \wp (a^\perp \otimes b^\perp), (b \otimes c) \wp d, c^\perp \otimes d^\perp}}
 \end{array}$$

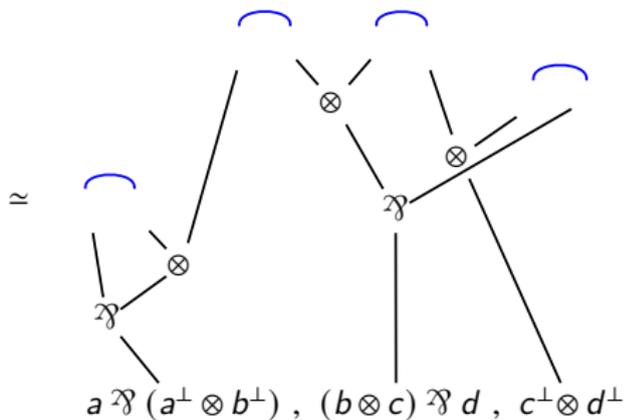
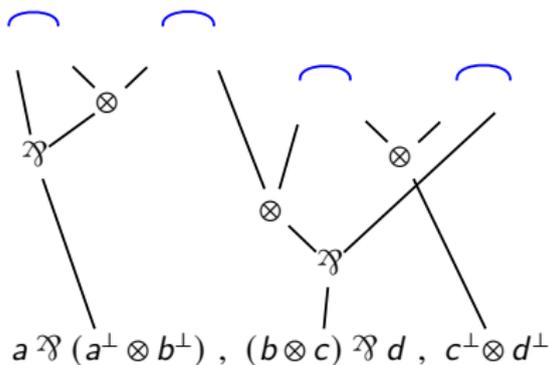
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The π -Calculus

Syntax and semantics of the π -calculus

$P, Q, R ::= \text{Nil}$ terminated prog.

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$P, Q, R ::=$	Nil	terminated prog.		
	$P \mid Q$	parallel	Par :	$P \mid Q \rightarrow P' \mid Q$ if $P \rightarrow P'$
	$(\nu x)P$	restriction (or nu)	Res :	$(\nu x)P \rightarrow (\nu x)P'$ if $P \rightarrow P'$

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	$x!(y).P$	send (y on x)			
	$x?(y).P$	receive (y on x)	Com :	$x!(a).P \mid x?(b).Q \rightarrow P \mid Q[a/b]$	

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	$P + Q$	Choice	Plus :	$(P + Q) \mid R \rightarrow P' \mid R'$	if $P \mid R \rightarrow P' \mid R'$

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	$x \triangleleft \{\ell : P_\ell\}_{\ell \in L}$	label-send (on x)	Choice :	$x \triangleleft \{\ell : P_\ell\}_{\ell \in L} \rightarrow x \triangleleft \{\ell_k : P_{\ell_k}\}$	if $\ell_k \in L$
	$x \triangleright \{\ell : P_\ell\}_{\ell \in L}$	label-receive (on x)	Sel :	$x \triangleleft \{\ell_k : P_{\ell_k}\} \mid x \triangleright \{\ell : Q_\ell\}_{\ell \in L} \rightarrow P_{\ell_k} \mid Q_{\ell_k}$	if $\ell_k \in L$

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$$\begin{array}{l}
 P \mid Q \Leftrightarrow Q \mid P \\
 (\nu x)(\nu y)P \Leftrightarrow (\nu y)(\nu x)P \\
 x \triangleleft \{\ell : (\nu y)P_\ell\}_{\ell \in L} \Leftrightarrow (\nu y)(x \triangleleft \{\ell : P_\ell\}_{\ell \in L}) \\
 (\nu x)S \Rightarrow S \\
 (P \mid Q) \mid R \Leftrightarrow P \mid (Q \mid R) \\
 P \mid \text{Nil} \Rightarrow P \\
 x \triangleright \{\ell : (\nu y)P_\ell\}_{\ell \in L} \Leftrightarrow (\nu y)(x \triangleright \{\ell : P_\ell\}_{\ell \in L}) \\
 (\nu x)P \mid S \Rightarrow (\nu x)(P \mid S)
 \end{array}$$

with $x \notin \text{free}(S)$

$$\text{Struc : } P \rightarrow Q \quad P \equiv P' \rightarrow Q' \equiv Q$$

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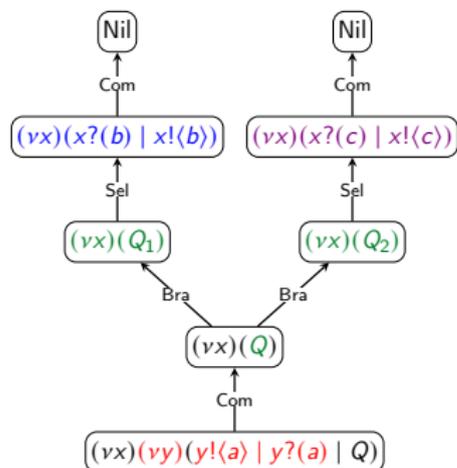
$$\text{Struc}^{\Rightarrow} : P \rightarrow Q \quad \left\{ \begin{array}{l} \text{if } P \Rightarrow^* P' = \mathcal{P}[S] \rightarrow \mathcal{P}[S'] = Q \\ \text{with } P \neq P' \text{ and } S \rightarrow S' \text{ not via } \text{Struc}^{\Rightarrow} \end{array} \right.$$

Example

$$(\forall x)(\forall y) \left(y \neq \langle a \rangle \mid y \neq \langle a \rangle \mid x \triangleright \left\{ \ell_1 : x \neq \langle b \rangle, \ell_2 : x \neq \langle c \rangle \right\} \mid x \triangleleft \left\{ \ell_1 : x \neq \langle b \rangle, \ell_2 : x \neq \langle c \rangle \right\} \right)$$

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$$(\nu x)(\nu y) \left(y!\langle a \rangle \mid y?(a) \mid x \triangleright \left\{ \ell_1 : x?(b), \ell_2 : x!\langle c \rangle \right\} \mid x \triangleleft \left\{ \ell_1 : x!\langle b \rangle, \ell_2 : x?(c) \right\} \right)$$

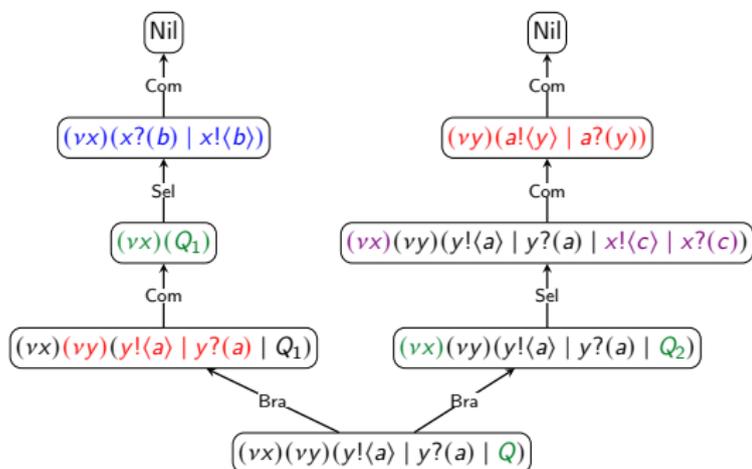


with

$$Q = x \triangleleft \begin{cases} \ell_1 : x?(b) \\ \ell_2 : c!\langle x \rangle \end{cases} \quad R = x \triangleright \begin{cases} \ell_1 : x!\langle b \rangle \\ \ell_2 : x?(c) \end{cases}$$
$$Q_1 = x \triangleleft \{ \ell_1 : x?(b) \} \quad Q_2 = x \triangleleft \{ \ell_2 : x!\langle c \rangle \}$$

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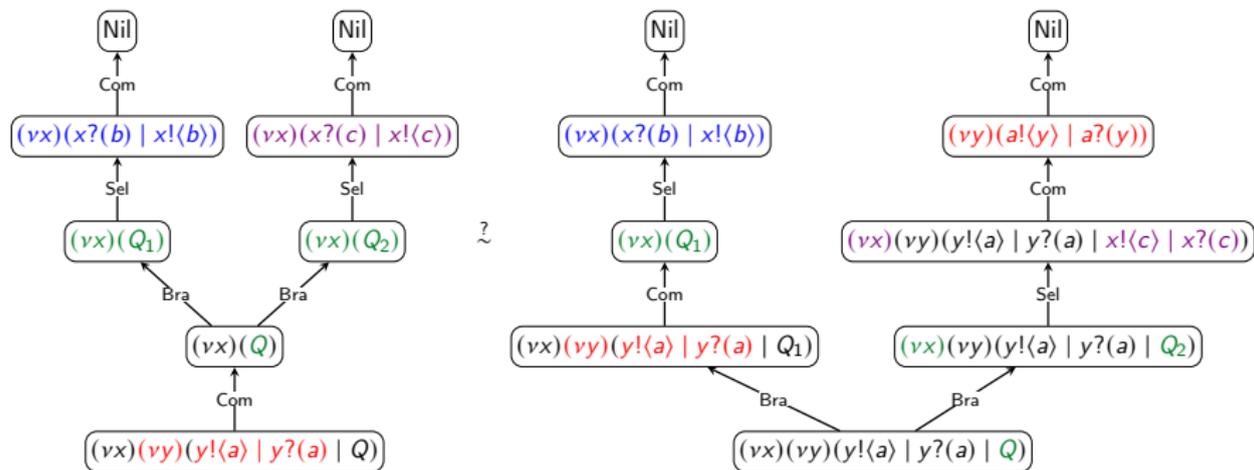


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$$Q_1 = x \triangleleft \left\{ \ell_1 : x?(b) \right\} \quad Q_2 = x \triangleleft \left\{ \ell_2 : x!\langle c \rangle \right\}$$

Example



Processes as Formulas

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$$\llbracket X \triangleleft \{\ell : P_\ell\}_{\ell \in L} \rrbracket = \bigotimes_{\ell \in L} (\llbracket P_\ell \rrbracket)$$

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- a “linear” approach to resources;
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- prefix operator (non-commutative, non-associative);

$$\llbracket \text{Nil} \rrbracket = \circ$$

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$$\llbracket x \triangleleft \{ \ell : P_\ell \}_{\ell \in L} \rrbracket = \bigotimes_{\ell \in L} (\llbracket P_\ell \rrbracket)$$

$$\llbracket x \triangleright \{ \ell : P_\ell \}_{\ell \in L} \rrbracket = \bigoplus_{\ell \in L} (\llbracket P_\ell \rrbracket)$$

$$\llbracket x! \langle y \rangle . P \rrbracket = \begin{cases} \langle x!y \rangle & \text{if } P = \text{Nil} \\ \langle x!y \rangle \blacktriangleleft \llbracket P \rrbracket & \text{if } P \neq \text{Nil} \end{cases}$$

$$\llbracket x? \langle y \rangle . P \rrbracket = \begin{cases} (x?y) & \text{if } P = \text{Nil} \\ (x?y) \blacktriangleleft \llbracket P \rrbracket & \text{if } P \neq \text{Nil} \end{cases}$$

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- parallel operator (commutative, associative);
- choice operators (one with priority over the other).
- prefix operator (non-commutative, non-associative);
- variable binding for input (existential quantifier);

$$\llbracket \text{Nil} \rrbracket = \circ$$

$$\llbracket P \mid Q \rrbracket = \llbracket P \rrbracket \wp \llbracket Q \rrbracket$$

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- prefix operator (non-commutative, non-associative);
- variable binding for input (existential quantifier);
- restriction operator (nominal quantifier);

$$\llbracket \text{Nil} \rrbracket = \circ$$

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Formulas

$A, B :=$

- | $\langle x!y \rangle$ atom
- | $\langle x?y \rangle$ atom
- | $A \wp B$ par
- | $A \otimes B$ tensor

$$\text{ax} \frac{}{\mathcal{S} \vdash \langle x!y \rangle, \langle x?y \rangle}$$

$$\wp \frac{\mathcal{S} \vdash \Gamma, A, B}{\mathcal{S} \vdash \Gamma, A \wp B}$$

$$\otimes \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash B, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, A \otimes B, \Delta}$$

$$\text{cut} \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash A^\perp, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta}$$

Formulas

- $A, B := \circ$ unit (atom)
- | $\langle x!y \rangle$ atom
- | $\langle x?y \rangle$ atom
- | $A \wp B$ par
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$$\text{ax} \frac{}{\mathcal{S} \vdash \langle x!y \rangle, \langle x?y \rangle}$$

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$$\circ \frac{}{\mathcal{S} \vdash \circ} \quad \text{mix} \frac{\mathcal{S}_1 \vdash \Gamma \quad \mathcal{S}_2 \vdash \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta}$$

Formulas

$A, B := \circ$	unit (atom)
$\langle x!y \rangle$	atom
$\langle x?y \rangle$	atom
$A \wp B$	par
$A \otimes B$	tensor
$A \oplus B$	oplus
$A \& B$	with

$$\text{ax} \frac{}{\mathcal{S} \vdash \langle x!y \rangle, \langle x?y \rangle} \quad \wp \frac{\mathcal{S} \vdash \Gamma, A, B}{\mathcal{S} \vdash \Gamma, A \wp B} \quad \otimes \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash B, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, A \otimes B, \Delta}$$

$$\text{cut} \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash A^\perp, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta}$$

$$\oplus \frac{\mathcal{S} \vdash \Gamma, A_i}{\mathcal{S} \vdash \Gamma, A_1 \oplus B_2} \quad \& \frac{\mathcal{S} \vdash \Gamma, A \quad \mathcal{S} \vdash \Gamma, B}{\mathcal{S} \vdash \Gamma, A \& B}$$

$$\circ \frac{}{\mathcal{S} \vdash \circ} \quad \text{mix} \frac{\mathcal{S}_1 \vdash \Gamma \quad \mathcal{S}_2 \vdash \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta}$$

Formulas	
$A, B := \circ$	unit (atom)
$\langle x!y \rangle$	atom
$\langle x?y \rangle$	atom
$A \wp B$	par
$A \otimes B$	tensor
$A \oplus B$	oplus
$A \& B$	with
$\forall x.A$	for all
$\exists x.A$	exists

$$\text{ax} \frac{}{\mathcal{S} \vdash \langle x!y \rangle, \langle x?y \rangle} \quad \wp \frac{\mathcal{S} \vdash \Gamma, A, B}{\mathcal{S} \vdash \Gamma, A \wp B} \quad \otimes \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash B, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, A \otimes B, \Delta} \quad \boxed{\text{cut} \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash A^\perp, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta}}$$

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$$\circ \frac{}{\mathcal{S} \vdash \circ} \quad \text{mix} \frac{\mathcal{S}_1 \vdash \Gamma \quad \mathcal{S}_2 \vdash \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta}$$

$$\text{ax} \frac{}{\mathcal{S} \vdash \langle x!y \rangle, \langle x?y \rangle} \quad \text{?y} \frac{\mathcal{S} \vdash \Gamma, A, B}{\mathcal{S} \vdash \Gamma, A \text{?} B} \quad \otimes \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash B, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, A \otimes B, \Delta} \quad \boxed{\text{cut} \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash A^\perp, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta}}$$

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$A \otimes B$	tensor
$A \blacktriangleleft B$	prec
$A \oplus B$	oplus
$A \& B$	with
$\forall x.A$	for all
$\exists x.A$	exists

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$$\circ \frac{}{\mathcal{S} \vdash \circ} \quad \text{mix} \frac{\mathcal{S}_1 \vdash \Gamma \quad \mathcal{S}_2 \vdash \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta} \quad \blacktriangleleft \frac{\mathcal{S}_1 \vdash \Gamma, A, C \quad \mathcal{S}_2 \vdash \Delta, B, D}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta, A \blacktriangleleft B, C \blacktriangleleft D} \quad \blacktriangleleft \circ \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash \Delta, B}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta, A \blacktriangleleft B}$$

$$\text{ax} \frac{}{\mathcal{S} \vdash \langle x!y \rangle, \langle x?y \rangle} \quad \text{?y} \frac{\mathcal{S} \vdash \Gamma, A, B}{\mathcal{S} \vdash \Gamma, A \text{?} B} \quad \otimes \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash B, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, A \otimes B, \Delta} \quad \boxed{\text{cut} \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash A^\perp, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta}}$$

Formulas

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$A \text{?} B$	par
$A \otimes B$	tensor
$A \blacktriangleleft B$	prec
$A \oplus B$	oplus
$A \& B$	with
$\forall x.A$	for all
$\exists x.A$	exists
$\text{И}x.A$	new
$\text{Я}x.A$	ya

$$\oplus \frac{\mathcal{S} \vdash \Gamma, A_i}{\mathcal{S} \vdash \Gamma, A_1 \oplus B_2} \quad \& \frac{\mathcal{S} \vdash \Gamma, A \quad \mathcal{S} \vdash \Gamma, B}{\mathcal{S} \vdash \Gamma, A \& B} \quad \exists \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S} \vdash \Gamma, \exists x.A} \quad \forall \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S} \vdash \Gamma, \forall x.A} \dagger$$

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$$\text{И}_\circ \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S} \vdash \Gamma, \text{И}x.A} \dagger \quad \text{И}_{\text{load}} \frac{\mathcal{S}, x^{\text{И}} \vdash \Gamma, A}{\mathcal{S} \vdash \Gamma, \text{И}x.A} \dagger \quad \text{И}_{\text{pop}} \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S}, y^{\text{И}} \vdash \Gamma, \text{Я}x.A}$$

$$\text{Я}_\circ \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S} \vdash \Gamma, \text{Я}x.A} \dagger \quad \text{Я}_{\text{load}} \frac{\mathcal{S}, x^{\text{Я}} \vdash \Gamma, A}{\mathcal{S} \vdash \Gamma, \text{Я}x.A} \dagger \quad \text{Я}_{\text{pop}} \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S}, y^{\text{Я}} \vdash \Gamma, \text{И}x.A}$$

$$\text{ax} \frac{}{\mathcal{S} \vdash \langle x!y \rangle, \langle x?y \rangle} \quad \text{?y} \frac{\mathcal{S} \vdash \Gamma, A, B}{\mathcal{S} \vdash \Gamma, A \text{?} B} \quad \otimes \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash B, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, A \otimes B, \Delta} \quad \boxed{\text{cut} \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash A^\perp, \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta}}$$

Formulas

$A, B := \circ$	unit (atom)
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$\text{I}x.A$	new
$\text{Я}x.A$	ya

$$\oplus \frac{\mathcal{S} \vdash \Gamma, A_i}{\mathcal{S} \vdash \Gamma, A_1 \oplus B_2} \quad \& \frac{\mathcal{S} \vdash \Gamma, A \quad \mathcal{S} \vdash \Gamma, B}{\mathcal{S} \vdash \Gamma, A \& B} \quad \exists \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S} \vdash \Gamma, \exists x.A} \quad \forall \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S} \vdash \Gamma, \forall x.A} \dagger$$

$$\circ \frac{}{\mathcal{S} \vdash \circ} \quad \text{mix} \frac{\mathcal{S}_1 \vdash \Gamma \quad \mathcal{S}_2 \vdash \Delta}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta} \quad \blacktriangleleft \frac{\mathcal{S}_1 \vdash \Gamma, A, C \quad \mathcal{S}_2 \vdash \Delta, B, D}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta, A \blacktriangleleft B, C \blacktriangleleft D} \quad \blacktriangleleft \frac{\mathcal{S}_1 \vdash \Gamma, A \quad \mathcal{S}_2 \vdash \Delta, B}{\mathcal{S}_1, \mathcal{S}_2 \vdash \Gamma, \Delta, A \blacktriangleleft B}$$

$$\text{I}_\circ \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S} \vdash \Gamma, \text{I}x.A} \dagger \quad \text{I}_{\text{load}} \frac{\mathcal{S}, x^{\text{H}} \vdash \Gamma, A}{\mathcal{S} \vdash \Gamma, \text{I}x.A} \dagger \quad \text{I}_{\text{pop}} \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S}, y^{\text{H}} \vdash \Gamma, \text{Я}x.A}$$

$$\text{Я}_\circ \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S} \vdash \Gamma, \text{Я}x.A} \dagger \quad \text{Я}_{\text{load}} \frac{\mathcal{S}, x^{\text{Я}} \vdash \Gamma, A}{\mathcal{S} \vdash \Gamma, \text{Я}x.A} \dagger \quad \text{Я}_{\text{pop}} \frac{\mathcal{S} \vdash \Gamma, A[y/x]}{\mathcal{S}, y^{\text{Я}} \vdash \Gamma, \text{I}x.A}$$

$$A \multimap B := A^\perp \text{?} B$$

PiL = all above rules except cut

Theorem

Let F be a formula. Then $\vdash_{\text{PiLU}\{\text{cut}\}} F \iff \vdash_{\text{PiL}} F$.

Theorem

If $\vdash_{\text{PiL}} A \multimap B$ and $\vdash_{\text{PiL}} B \multimap C$, then $\vdash_{\text{PiL}} A \multimap C$.

Theorem

The following logical equivalences and implications are derivable in PiL.

$$(A \blacktriangleleft B) \multimap (A \wp B) \qquad (A \wp \circ) \multimap (A \blacktriangleleft \circ) \multimap (\circ \blacktriangleleft A) \multimap (A \otimes \circ) \multimap A$$

$$((A \odot B) \odot C) \multimap (A \odot (B \odot C)) \qquad (A \odot B) \multimap (B \odot A) \quad \text{for all } \odot \in \{\wp, \otimes, \oplus, \&\}$$

$$((A \& C) \wp (B \& C)) \multimap (A \& B) \wp C \qquad \exists x.(A \wp B) \multimap (\exists x.A) \wp B \quad \text{if } x \notin \text{free}(B)$$

Proofs in PiL as computation trees

Theorem

- If $P \Rightarrow Q$, then $\llbracket Q \rrbracket \dashv\vdash \llbracket P \rrbracket$
- If $P \rightarrow Q$ via Com or Sel, then $\llbracket Q \rrbracket \dashv\vdash \llbracket P \rrbracket$
- If " $P \rightarrow \{Q_\ell\}_{\ell \in L}$ " via Bra, then $(\&_{\ell \in L} \llbracket Q_\ell \rrbracket) \dashv\vdash \llbracket P \rrbracket$;

Theorem

If P is race-free, then P is deadlock-free iff $\vdash_{\text{PiL}} \llbracket P \rrbracket$.

Lemma

For each computation tree \mathcal{T} of P there is a derivation $\mathcal{D}_{\mathcal{T}}$ with conclusion $\llbracket P \rrbracket$ in PiL.

Idea:

$$\begin{array}{c}
 \left((vx)(v\tilde{y}) (P \mid Q[a/b] \mid R) \right) \\
 \uparrow \text{Com} \\
 \left((vx)(v\tilde{y}) (x! \langle a \rangle . P \mid x? \langle b \rangle . Q \mid R) \right)
 \end{array}
 =
 \frac{\frac{\text{ax} \frac{}{\vdash \langle x!a \rangle, (x?a)} \quad \frac{}{\vdash \llbracket P \rrbracket, \llbracket Q[a/b] \rrbracket, \llbracket R \rrbracket}}{\vdash \langle x!a \rangle \triangleleft \llbracket P \rrbracket, (x?a) \triangleleft \llbracket Q[a/b] \rrbracket, \llbracket R \rrbracket} \quad \|\{\exists, I_o, \text{mix}, o\}}}{\vdash \langle x!a \rangle \triangleleft \llbracket P \rrbracket, \exists b. ((x?b) \triangleleft \llbracket Q \rrbracket), \Gamma} \quad \exists}{\vdash \llbracket (vx)(v\tilde{y}) (x! \langle a \rangle . P \mid x? \langle b \rangle . Q \mid R) \rrbracket}$$

$$\begin{array}{c}
 \left((vx)(v\tilde{y}) (P_{\ell_k} \mid Q_{\ell_k} \mid R) \right) \\
 \uparrow \text{Sel} \\
 \left((vx)(v\tilde{y}) (x \triangleleft \{ \ell_k : P_{\ell_k} \} \mid x \triangleright \{ \ell : Q_{\ell} \}_{\ell \in L} \mid R) \right)
 \end{array}
 =
 \frac{\frac{\text{ax} \frac{}{\vdash \langle x! \ell_k \rangle, (x? \ell_k)} \quad \frac{}{\vdash \llbracket P_{\ell_k} \rrbracket, \llbracket Q_{\ell_k} \rrbracket, \llbracket R \rrbracket}}{\vdash \langle x! \ell_k \rangle \triangleleft \llbracket P_{\ell_k} \rrbracket, (x? \ell_k) \triangleleft \llbracket Q_{\ell_k} \rrbracket, \llbracket R \rrbracket} \quad \|\{\exists, I_o, \text{mix}, o\}}}{\frac{\oplus}{\vdash \langle x! \ell_k \rangle \triangleleft \llbracket P_{\ell_k} \rrbracket, \bigoplus_{\ell \in L} ((x? \ell) \triangleleft \llbracket Q_{\ell} \rrbracket), \llbracket R \rrbracket}} \quad \oplus}{\vdash \llbracket (vx)(v\tilde{y}) (x \triangleleft \{ \ell_k : P_{\ell_k} \} \mid x \triangleright \{ \ell : Q_{\ell} \}_{\ell \in L} \mid R) \rrbracket}$$

Completeness of Choreographic Programming

Theorem

Let P be deadlock-free, then there is a choreography C such that $P = \text{EPP}(C)$.

Proof sketch

- P be deadlock-free \Rightarrow exists a successful computation tree \mathcal{T}
- \mathcal{T} successful computation tree \Rightarrow exists $\mathcal{D}_{\mathcal{T}}$ derivation in PiL of $\llbracket P \rrbracket$
- using permutations \Rightarrow there is a derivation \mathcal{D} of $\llbracket P \rrbracket$ made of blocks as the following [also other shapes]:

$$\frac{\text{ax} \frac{\frac{\frac{}{\vdash \langle (k!x) \rangle_p, \langle (k?x) \rangle_q}}{\vdash \Gamma, \langle (k!x) \blacktriangleleft \llbracket S \rrbracket \rangle_p, \langle (k?x) \blacktriangleleft \llbracket S' \rrbracket [x/y] \rangle_q}}{\vdash \Gamma, \langle (k!x) \blacktriangleleft \llbracket S \rrbracket \rangle_p, \langle (k?x) \blacktriangleleft \llbracket S' \rrbracket [x/y] \rangle_q}}{\exists \vdash \Gamma, \langle (k!x) \blacktriangleleft \llbracket S \rrbracket \rangle_p, \langle \exists y. \langle (k?y) \blacktriangleleft \llbracket S' \rrbracket \rangle_q}} \quad \mathbb{I} \mathcal{D}'$$

$$\& \frac{\left\{ \text{ax} \frac{\frac{\frac{}{\vdash \langle (k!l) \rangle_p, \langle (k?l) \rangle_q}}{\vdash \Gamma, \langle (k!l) \blacktriangleleft \llbracket S_l \rrbracket \rangle_p, \langle (k?l) \blacktriangleleft \llbracket S'_l \rrbracket \rangle_q}}{\vdash \Gamma, \langle (k!l) \blacktriangleleft \llbracket S_l \rrbracket \rangle_p, \langle (k?l) \blacktriangleleft \llbracket S'_l \rrbracket \rangle_q}} \right\}_{\ell \in L}}{\vdash \Gamma, \left(\&_{\ell \in L} \langle (k!l) \blacktriangleleft \llbracket S_l \rrbracket \rangle \right)_p, \left(\bigoplus_{\ell \in L'} \langle (k?l) \blacktriangleleft \llbracket S'_l \rrbracket \rangle \right)_q}_{\ell \in L}$$

Theorem

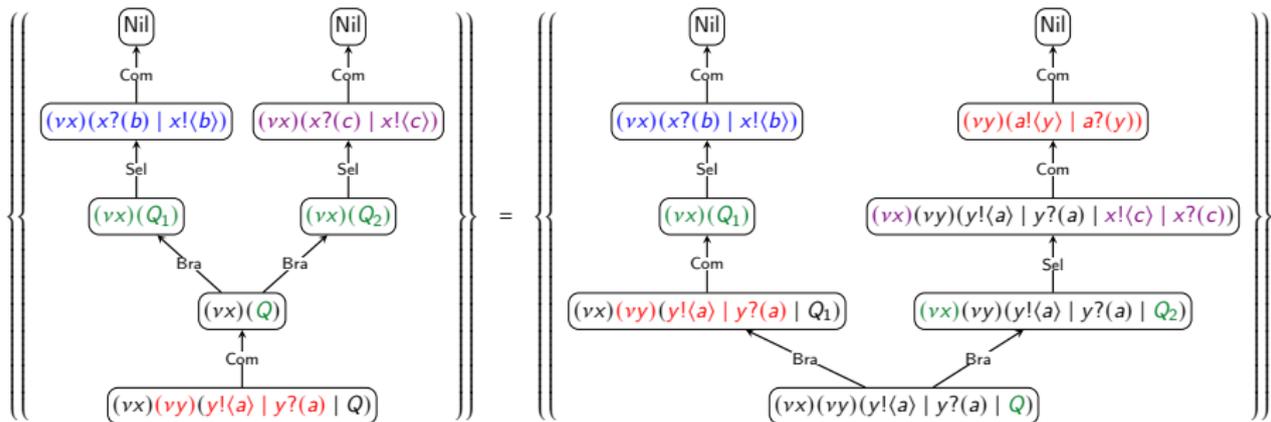
Let P be deadlock-free, then there is a choreography C such that $P = \text{EPP}(C)$.

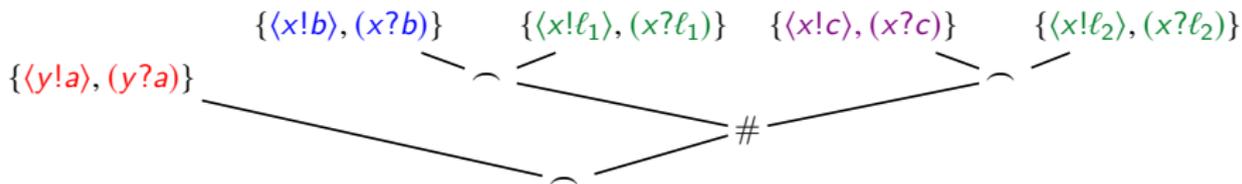
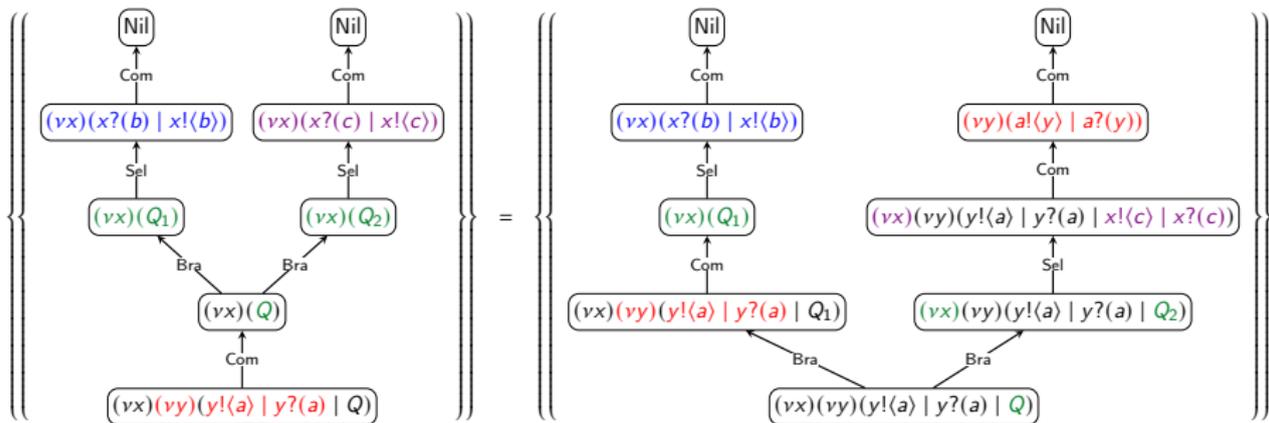
Proof sketch

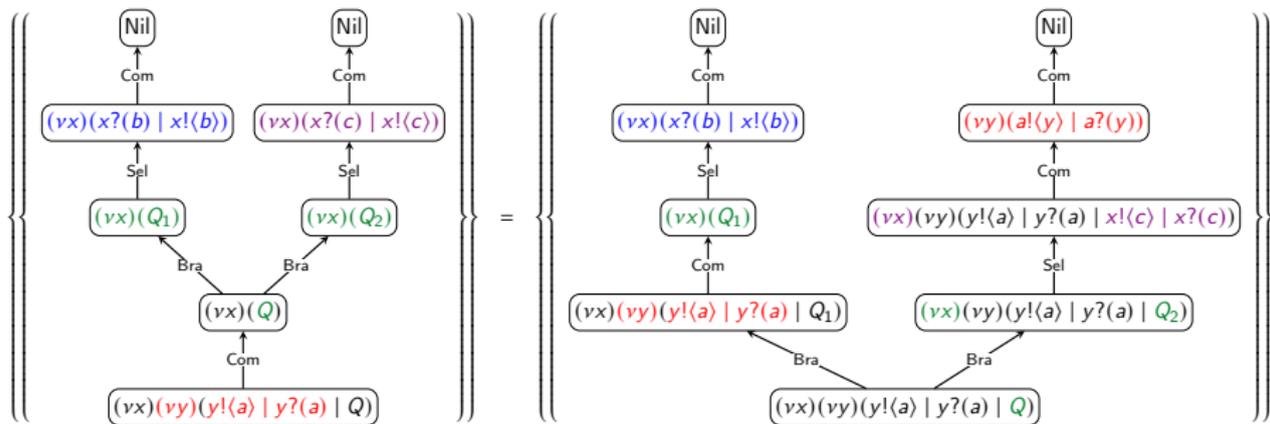
- P be deadlock-free \Rightarrow exists a successful computation tree \mathcal{T}
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$[p.x \rightarrow q.y]; C_{\mathcal{D}'}$	$p.L \rightarrow q.L' : k \left\{ \begin{array}{l} \ell : C_{\mathcal{D}_\ell} \mid \ell \in L \\ \ell : S'_\ell \mid \ell \in L' \setminus L \end{array} \right\}$

Proof nets







$$\left\{ \left\{ \langle y!a \rangle, \langle y?a \rangle \right\}, \left\{ \langle x!b \rangle, \langle x?b \rangle \right\}, \left\{ \langle x!l_1 \rangle, \langle x?l_1 \rangle \right\} \right\}, \left\{ \left\{ \langle y!a \rangle, \langle y?a \rangle \right\}, \left\{ \langle x!c \rangle, \langle x?c \rangle \right\}, \left\{ \langle x!l_2 \rangle, \langle x?l_2 \rangle \right\} \right\}$$

Conclusion and Future work

Main results:

- PiL + cut-free sequent calculus
- Computation trees of $P \rightsquigarrow$ Derivations in PiL of $\llbracket P \rrbracket$;
- Deadlock-freedom P (for race-free) = provability of $\llbracket P \rrbracket$ in PiL;
- Choreographic extraction using PiL (choreographies-as-proofs);
- Completeness result for choreographies wrt deadlock-freedom;
- Conflict nets and slice nets for PiL;
- Correspondence between computation trees (modulo) and proof nets.

What next?

- *Recursion* using fixpoints operators

Replication	Iteration	recursion
$?b \frac{S \vdash \Gamma, A, ?A}{S \vdash \Gamma, ?A}$	$!b \frac{S \vdash \Gamma, A \blacktriangleleft !A}{S \vdash \Gamma, !A}$	$\mu \frac{S \vdash \Gamma, P(\mu A)}{S \vdash \Gamma, \mu A.P(A)}$

- *Test preorders* as notions of orthogonality for proof nets;
 - Asynchronous π -calculus: use message buffers (similar to Concurrent Constraint Programming)
- Note: graphical connectives may be needed to model non-SP behaviors

$$\left(\begin{array}{cc} a & b \\ \downarrow & \searrow \\ c & d \end{array} \quad = N(|a, b, c, d|) \right)$$

Thanks

Thanks

Questions?